

Study of thermo-elastic effects in laminated composites by the cohesive zone model

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Introduction



- Cohesive Zone Model
- Extension to coupled thermoelastic problems

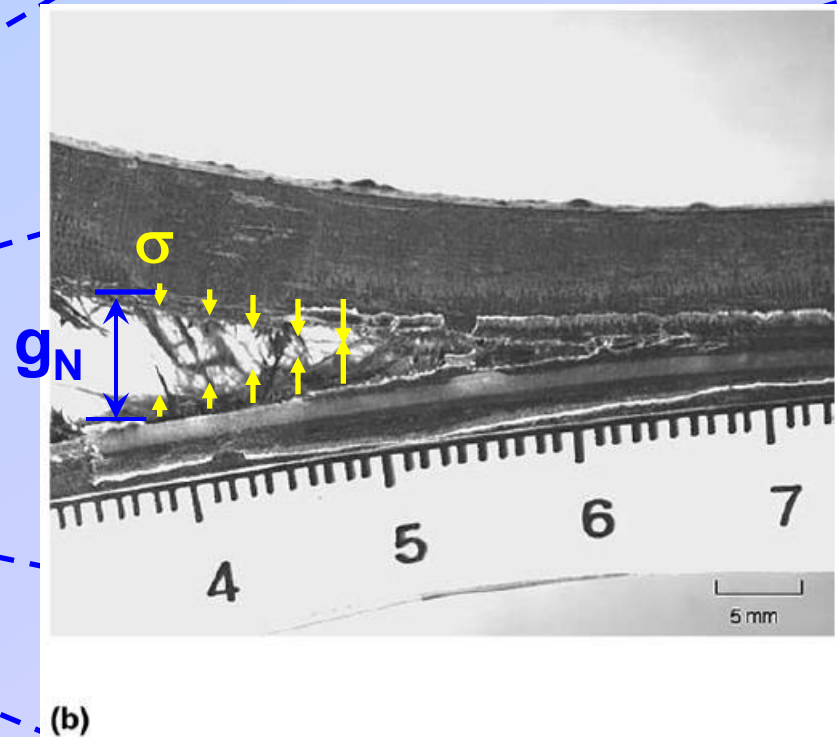
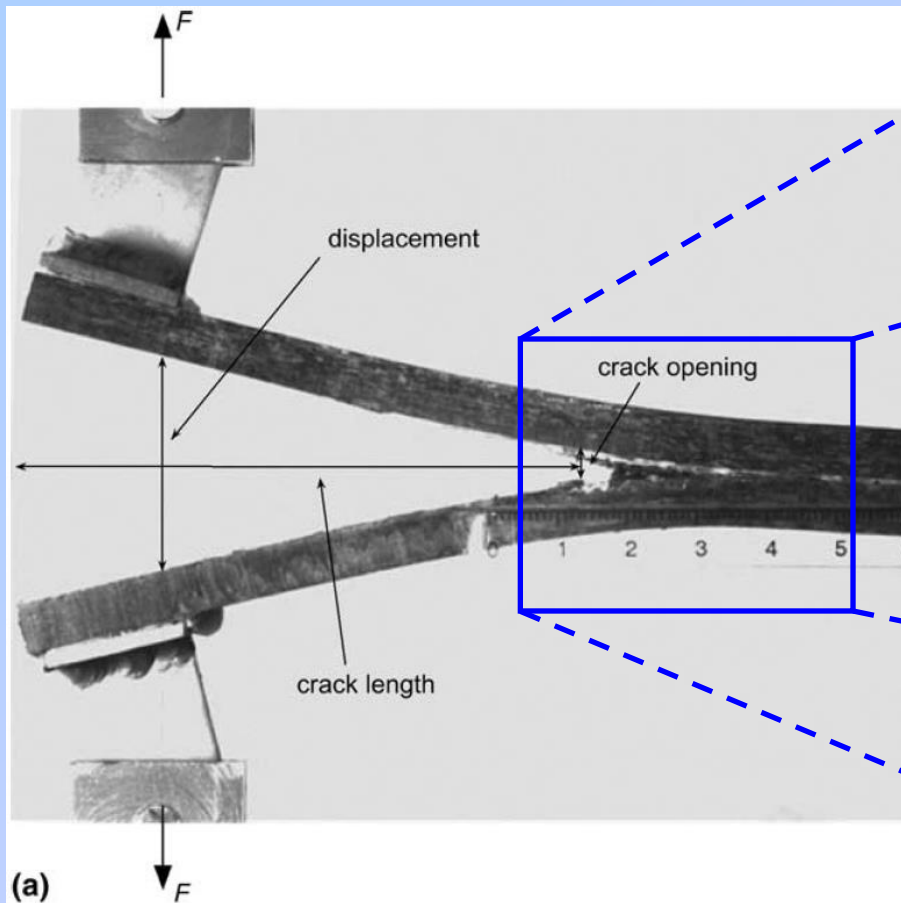
Traction-opening relations are taken into account and combined with heat flux-opening relations based on contact mechanics

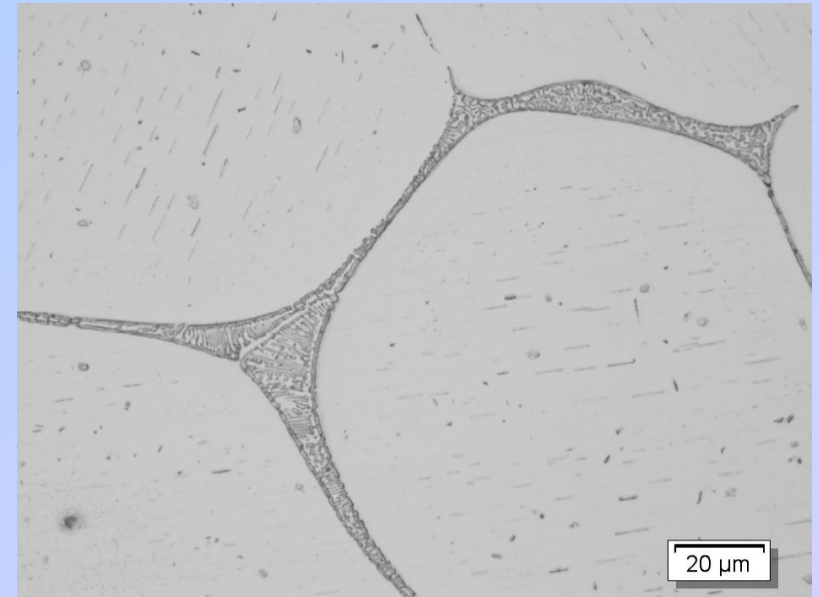
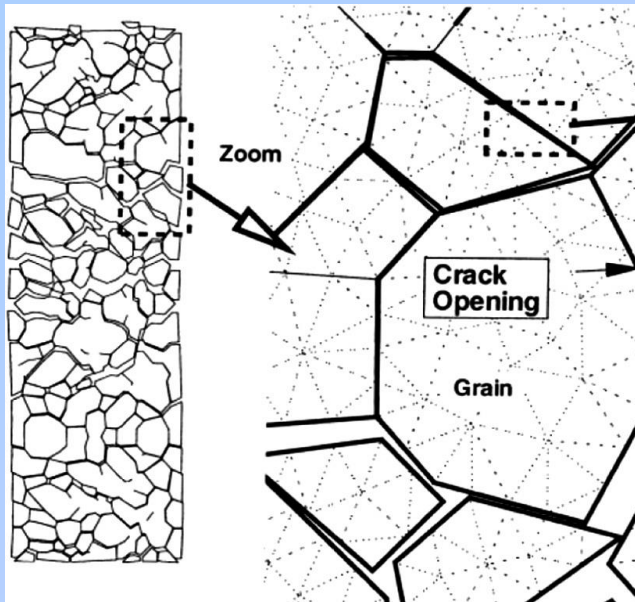
The purpose is twofold :

1. To generalize thermoelastic contact analysis to fracture
(Zavarise et al. 1992; Wriggers and Zavarise, 1993)
2. To propose a thermal model more physically sound than the others presented in the Literature (es. Kapitza's model)
(Hattiangadi&Siegmund 2004; Yvonnet et al. 2010; Özdemir et al., 2010)

- Conclusions

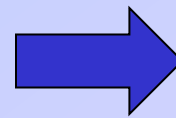
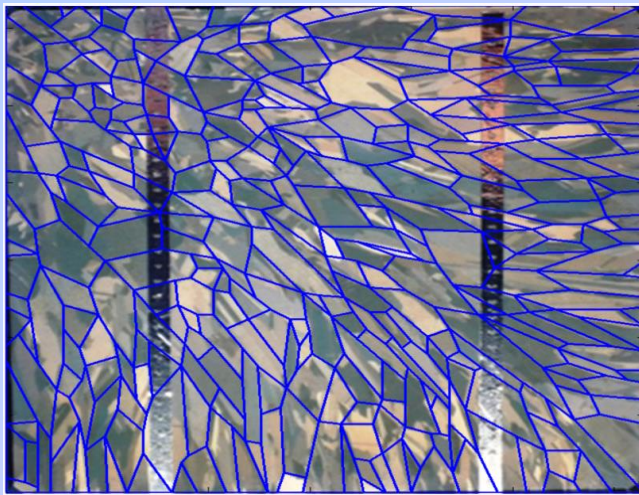
Double cantilever beam test





MgCa0.8: biomedical stents

Paggi et al., *Computational Mechanics* (2012)

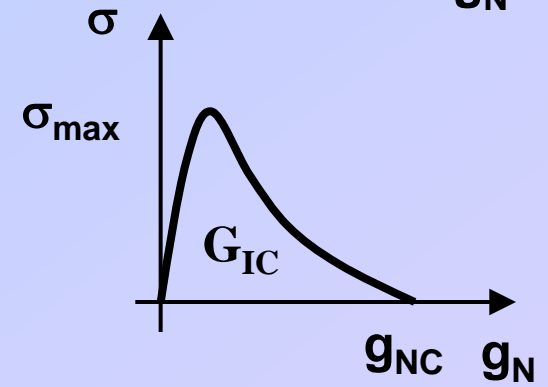
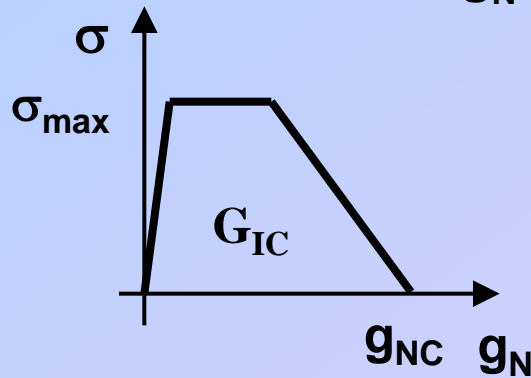
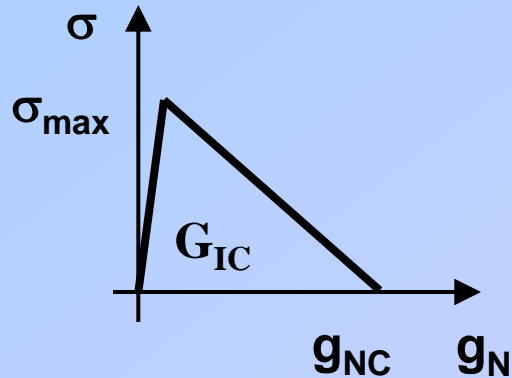
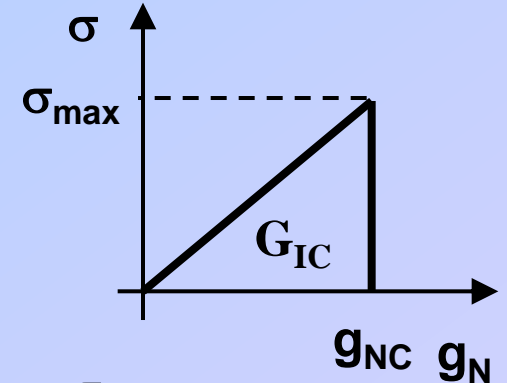
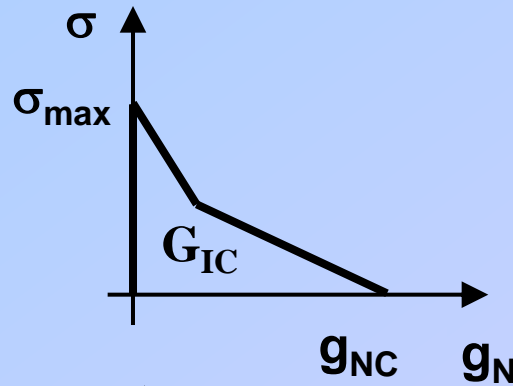
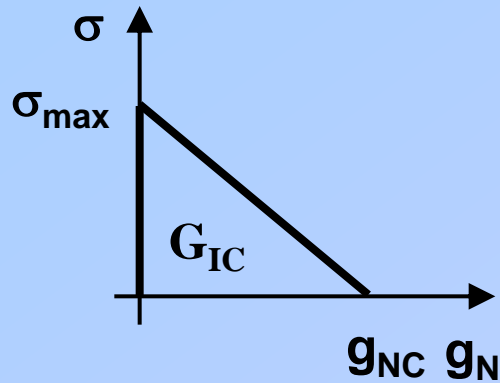


Silicon cells: photovoltaic modules

Paggi and Sapor, *Energy Procedia* (2013)



CZM: constitutive law

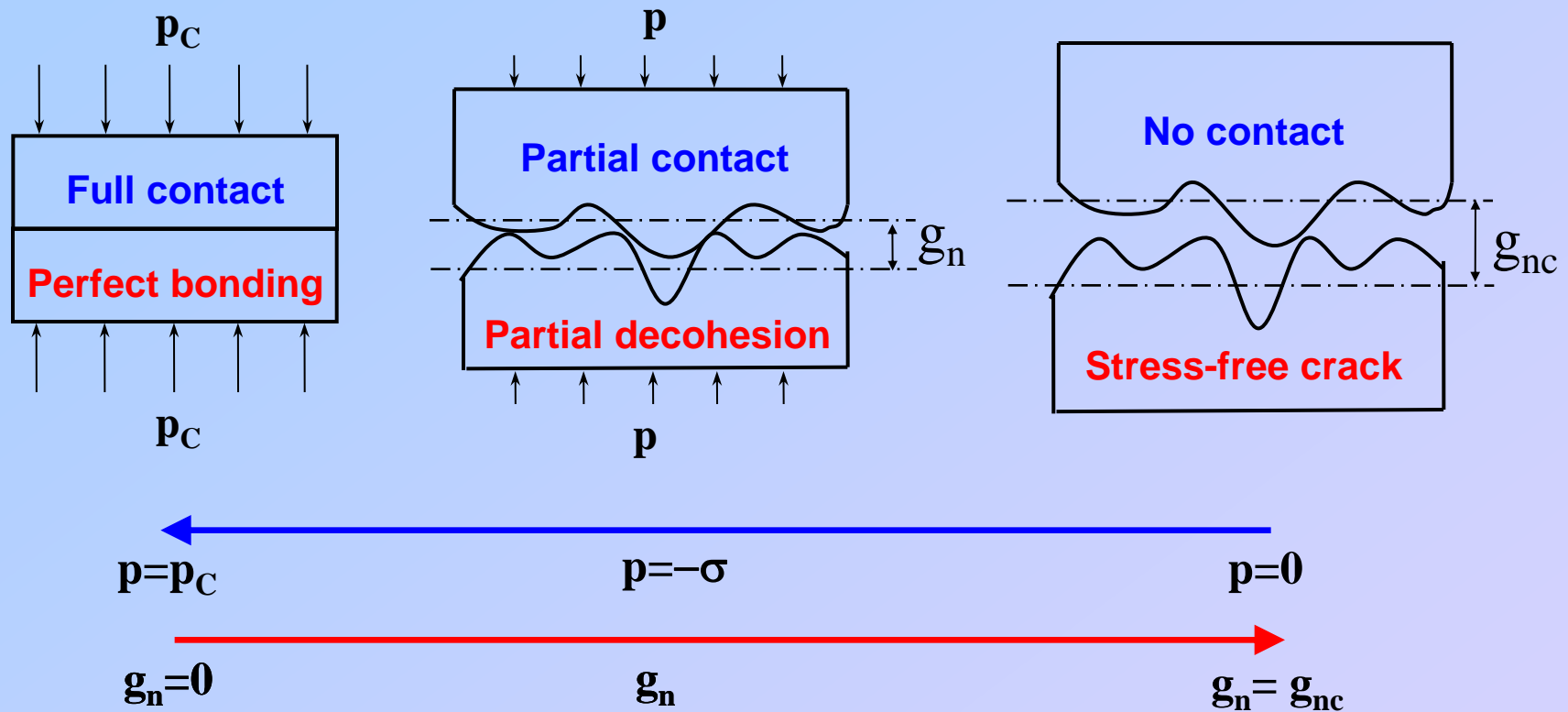


Open issues:

How is possible to relate the shape of the CZM to physics/mechanics?



Fracture / contact mechanics



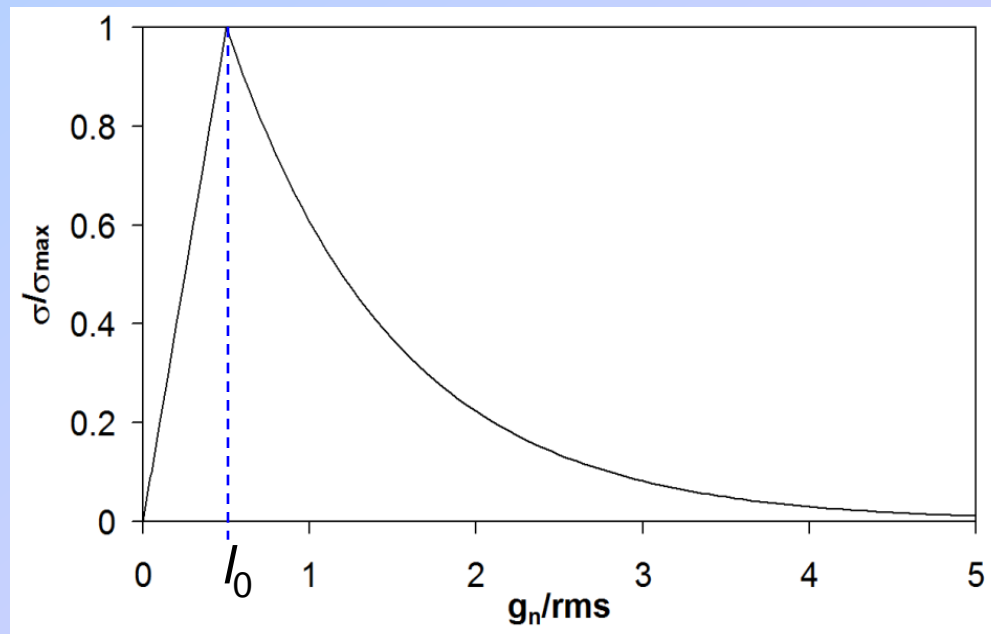
The introduction of “rms”, the root mean square of asperity heights reveals to be necessary for an accurate analysis..



Cohesive stress



$$\sigma = \begin{cases} \sigma_{\max} \exp\left(\frac{-l_0 - g_t}{\text{rms}}\right) \frac{g_n}{l_0} & \text{if } 0 \leq \frac{g_n}{\text{rms}} < \frac{l_0}{\text{rms}} \\ \sigma_{\max} \exp\left(\frac{-g_n - g_t}{\text{rms}}\right) & \text{if } \frac{l_0}{\text{rms}} \leq \frac{g_n}{\text{rms}} < \frac{g_{nc}}{\text{rms}} \\ 0 & \text{if } \frac{g_n}{\text{rms}} \geq \frac{g_{nc}}{\text{rms}} \end{cases}$$



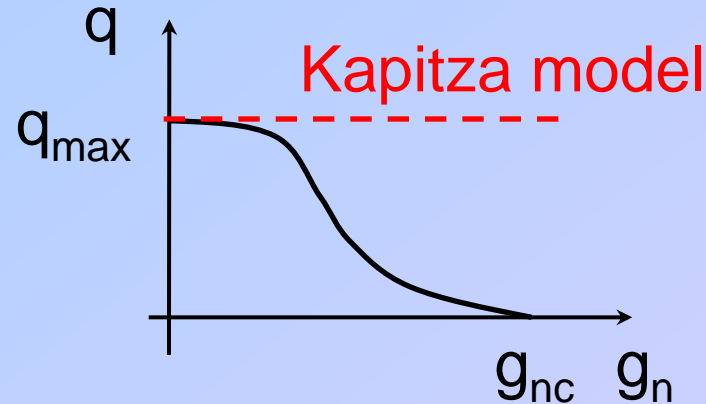
Greenwood and Williamson, *Proceedings of the Royal Society of London* (1966)



Cohesive heat flux

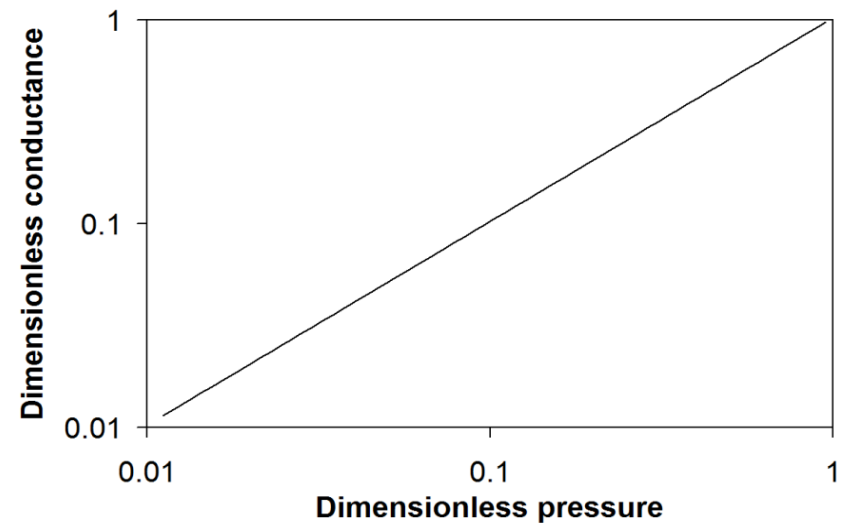


$$q = -k_{\text{int}}(g_n) \Delta T$$



N.B. Interface conductance proportional to the normal stiffness:

$$k_{\text{int}} = \begin{cases} \frac{1}{r_{\text{int}}} & \text{if } 0 \leq \frac{g_n}{\text{rms}} < \frac{l_0}{\text{rms}} \\ \frac{2\sigma}{r_{\text{int}} E_{\text{int}} \text{rms}} & \text{if } \frac{l_0}{\text{rms}} \leq \frac{g_n}{\text{rms}} < \frac{g_{\text{nc}}}{\text{rms}} \\ 0 & \text{if } \frac{g_n}{\text{rms}} \geq \frac{g_{\text{nc}}}{\text{rms}} \end{cases}$$

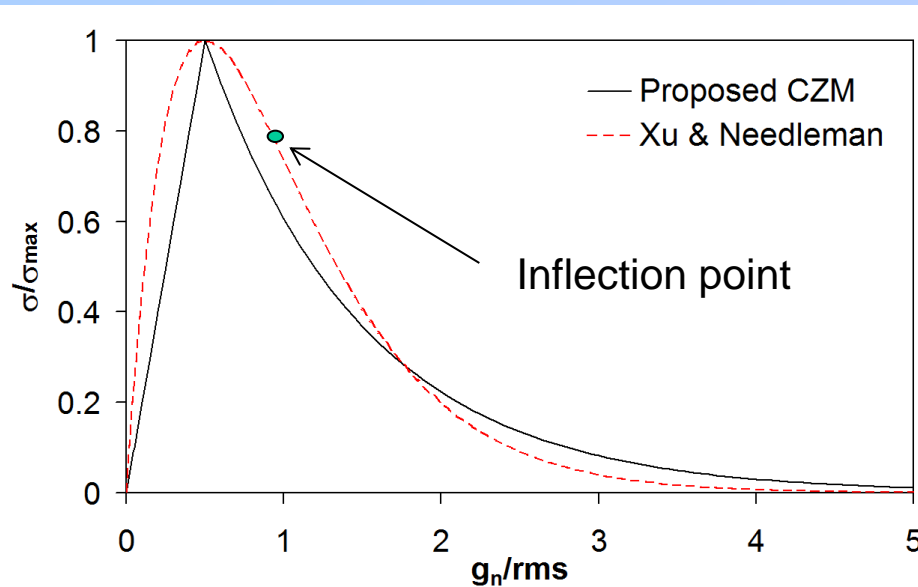




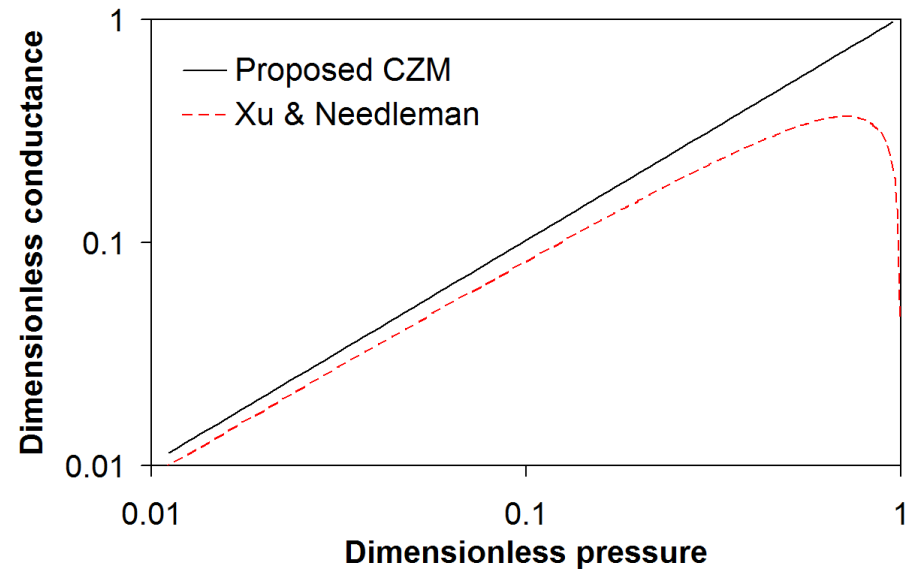
Comparison with other models



Stress



Conductance



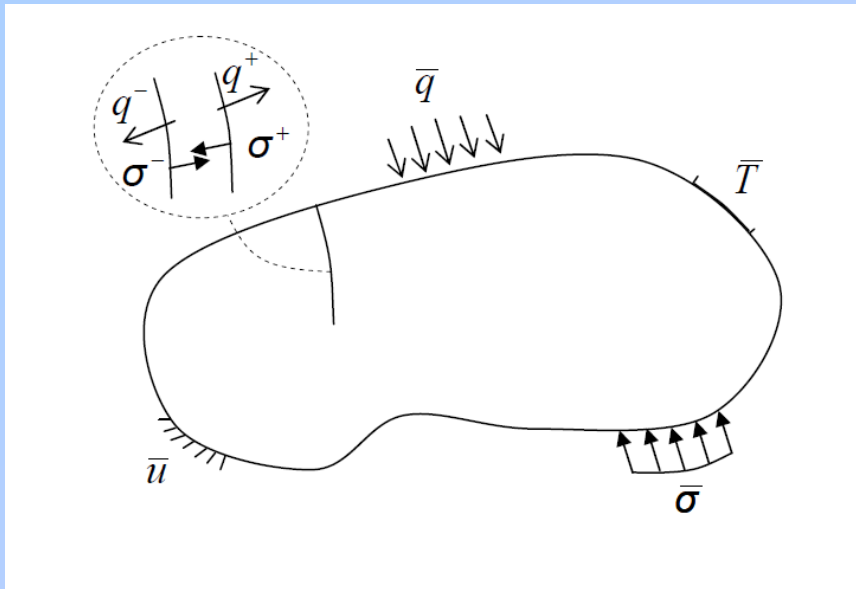
$$(l_0/rms = 0.5)$$

Xu and Needleman, *Journal of the Mechanics and Physics of Solids* (1994)

Özdemir et al. *Computational Mechanics* (2010)



Formulation of the problem: 1



V : volume

S : surface

\mathbf{S} : Cauchy stress tensor

\mathbf{f} : body force vector

\mathbf{w} : displacement vector

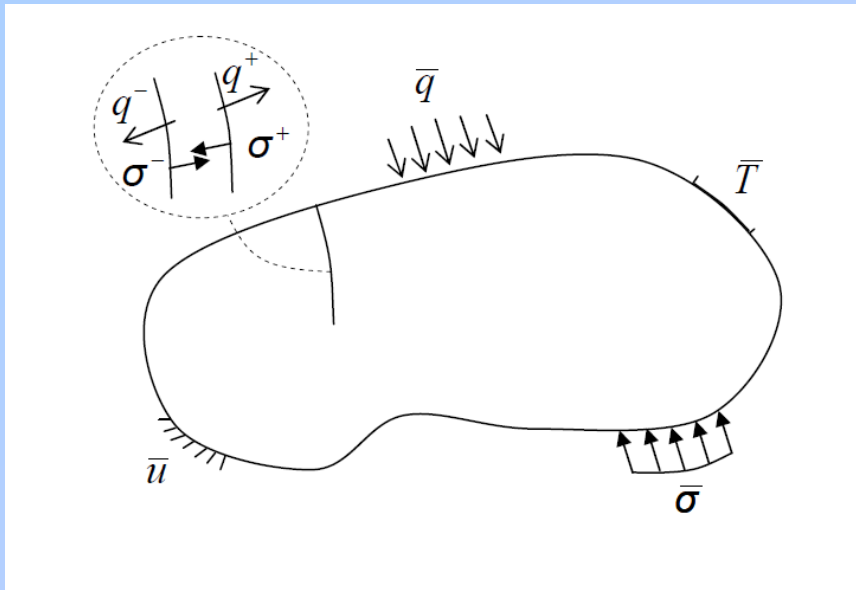
Strong form: $\nabla^T \mathbf{S} + \mathbf{f} = \mathbf{0}$

Weak form (PVW):

$$\int_V \mathbf{S} : \nabla(\delta \mathbf{w}) dV = \int_V \mathbf{f}^T (\delta \mathbf{w}) dV + \int_S \bar{\boldsymbol{\sigma}}^T (\delta \mathbf{w}) dS + \int_{S_{\text{int}}} \boldsymbol{\sigma}^T (\delta \mathbf{w}) dS$$



Formulation of the problem: 2



V : volume

S : surface

\mathbf{q} : heat flux vector

Q : heat generation

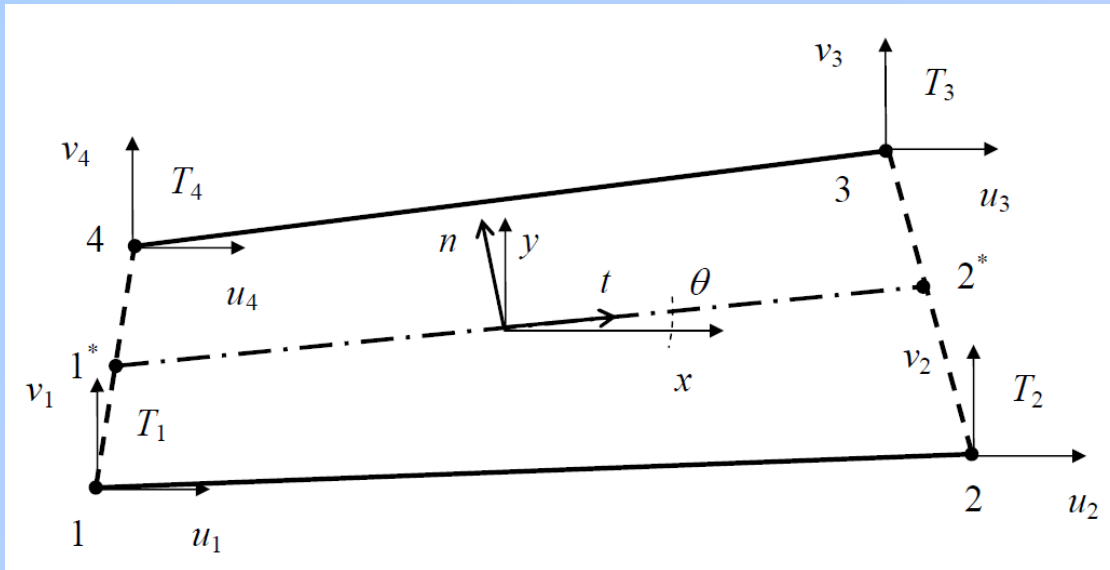
T : temperature

Strong form:

$$-\nabla^T \mathbf{q} + Q = \rho c \dot{T}$$

Weak form (variational form of the energy balance):

$$\int_V \mathbf{q}^T \nabla(\delta T) dV = \int_V (\rho c \dot{T} - Q) \delta T dV + \int_S \bar{\mathbf{q}}^T (\delta \mathbf{w}) dS + \int_{S_{\text{int}}} q(\delta T) dS$$



Gap vector:
 $\mathbf{g} = (g_t, g_n, g_T)^T$

Flux vector:
 $\mathbf{p} = (\tau, \sigma, q)^T$

Weak form for the interface elements:

$$\delta G_{\text{int}} = \int_{S_{\text{int}}} \delta \mathbf{g}^T \mathbf{p} dS$$

Consistent linearization of the interface constitutive law
 (quadratic convergence in the Newton-Raphson scheme):

$$\mathbf{p} = \mathbf{C} \mathbf{g} \quad \longrightarrow \quad \delta G_{\text{int}} = \int_{S_{\text{int}}} \delta \mathbf{g}^T \mathbf{C} \mathbf{g} dS$$



FEA: constitutive matrix C



$$\mathbf{C} = \begin{bmatrix} \frac{\partial \tau}{\partial g_t} & \frac{\partial \tau}{\partial g_n} & 0 \\ \frac{\partial \sigma}{\partial g_t} & \frac{\partial \sigma}{\partial g_n} & 0 \\ \frac{\partial q}{\partial g_t} & \frac{\partial q}{\partial g_n} & \frac{\partial q}{\partial g_T} \end{bmatrix}$$

Diagram illustrating the structure of the constitutive matrix \mathbf{C} :

- The top two rows (shear and normal stresses) are grouped by a bracket labeled **CZM**.
- The bottom row (heat flux) is grouped by a bracket labeled **Thermoelastic effect**.
- A dashed vertical line separates the stress components from the heat flux component.
- A dashed horizontal line separates the stress components from the heat flux component.
- A blue circle highlights the terms $\frac{\partial q}{\partial g_t}$ and $\frac{\partial q}{\partial g_n}$.

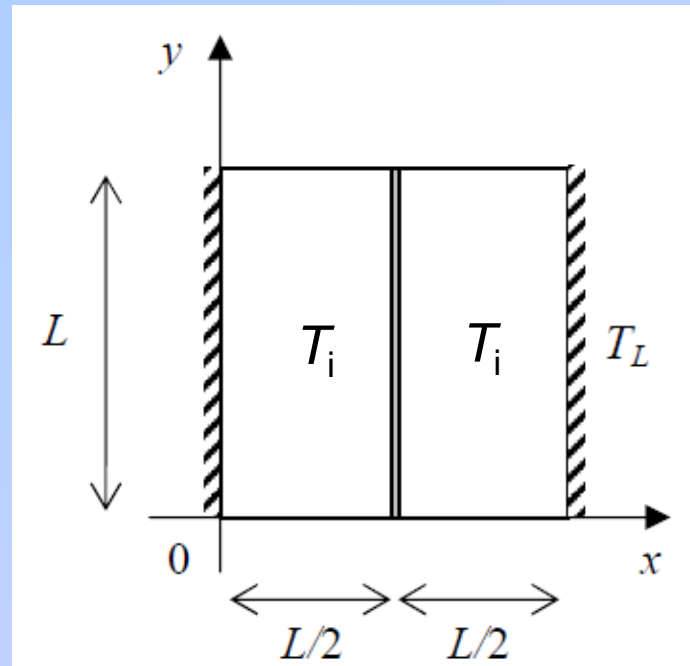
N.B. if we consider $k_{int}=const$ (Kapitza's model): $\frac{\partial q}{\partial g_t} = \frac{\partial q}{\partial g_n} = 0$

Tangent matrix for the Newton Raphson algorithm:

$$\mathbf{K} = \mathbf{R}^T \int_{S_{int}} \mathbf{B}^T \mathbf{C} \mathbf{B} dS \mathbf{R}$$



Parametric analysis



$$\begin{aligned}T_L &< T_i \\ y^* &= y/L = 0.5 \\ l_o/rms &= 0.01 \\ \nu &= 0.1\end{aligned}$$

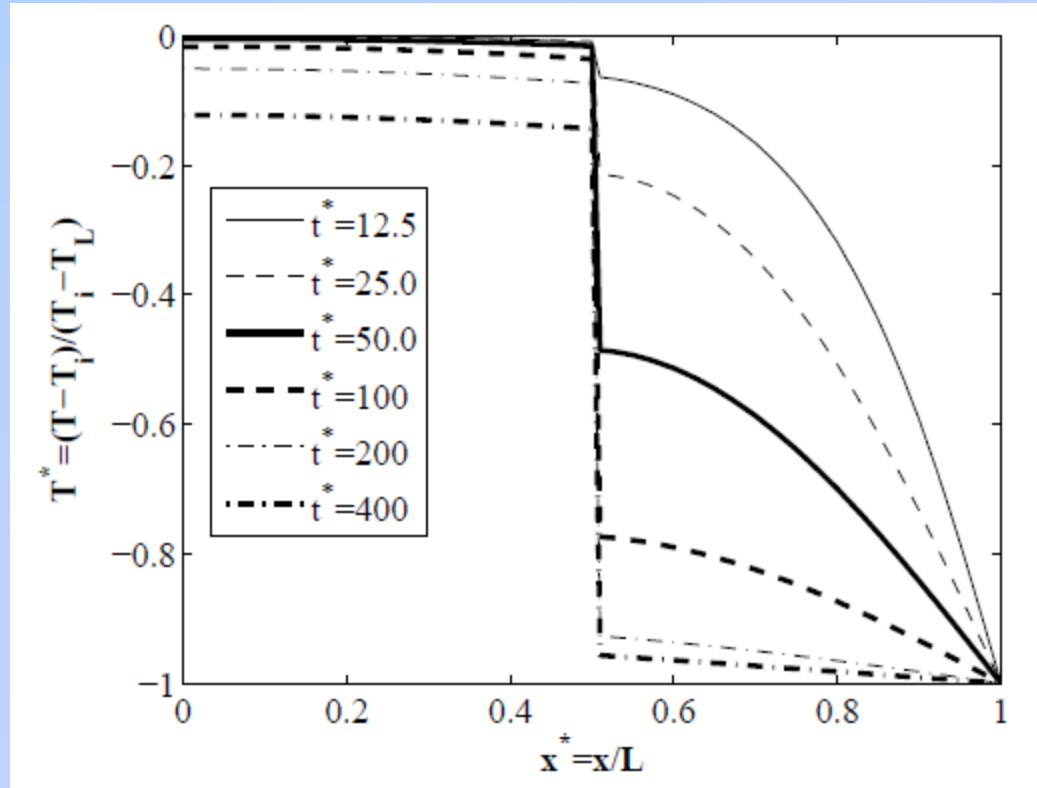
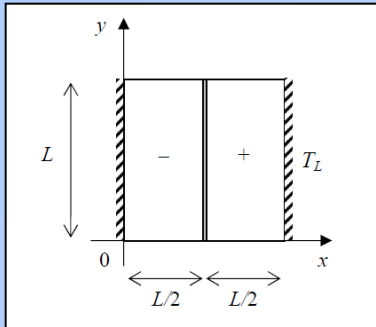
Let us focus our attention on the transient regime. Buckingham's Theorem allows us reducing the dependency of T^* (combination of T , T_i and T_L) to four parameters:

$$T^* = T^* \left(x^* = \frac{x}{L}, t^* = \frac{tD}{L^2}, g_{nc}^* = \frac{g_{nc}}{L}, \sigma_{max}^* = \frac{\sigma_{max}}{E} \right)$$



Results 1

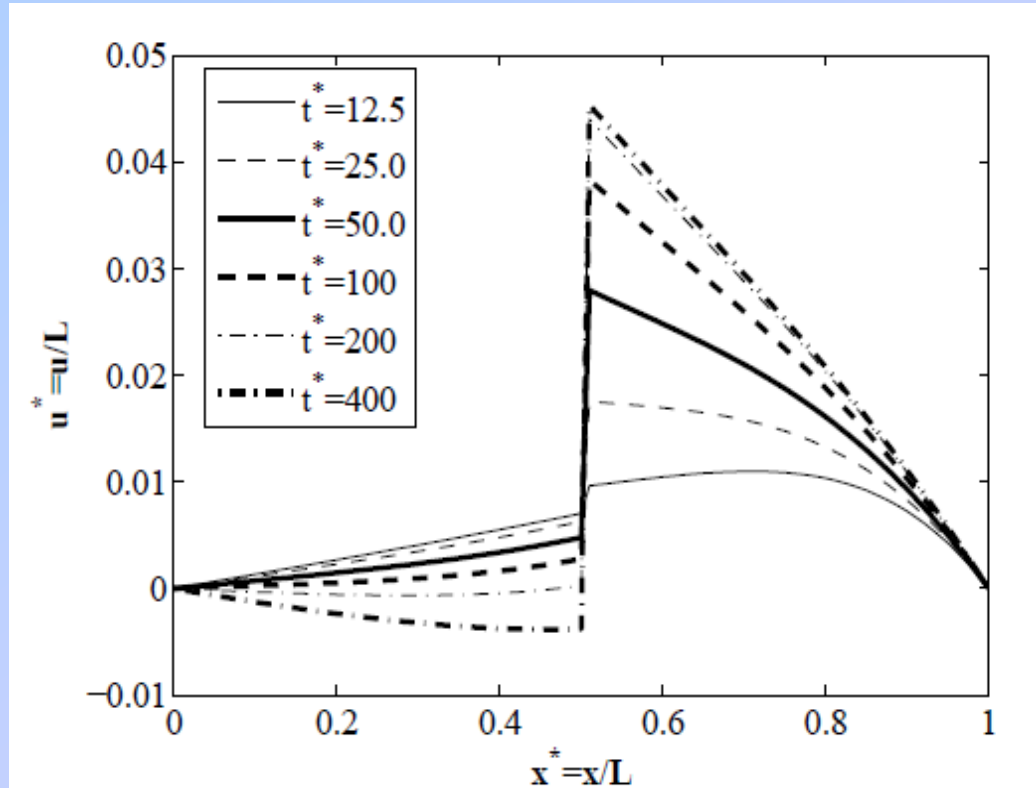
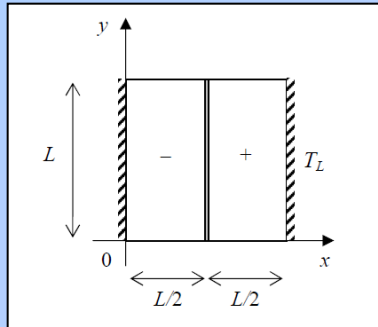
Temperature field as time varies ($y^* = y/L = 0.5$)



$$\sigma_{max}^* = 0.032, \quad g_{nc}^* = 0.05$$

Results 2

Displacement field as time varies ($y^* = y/L = 0.5$)

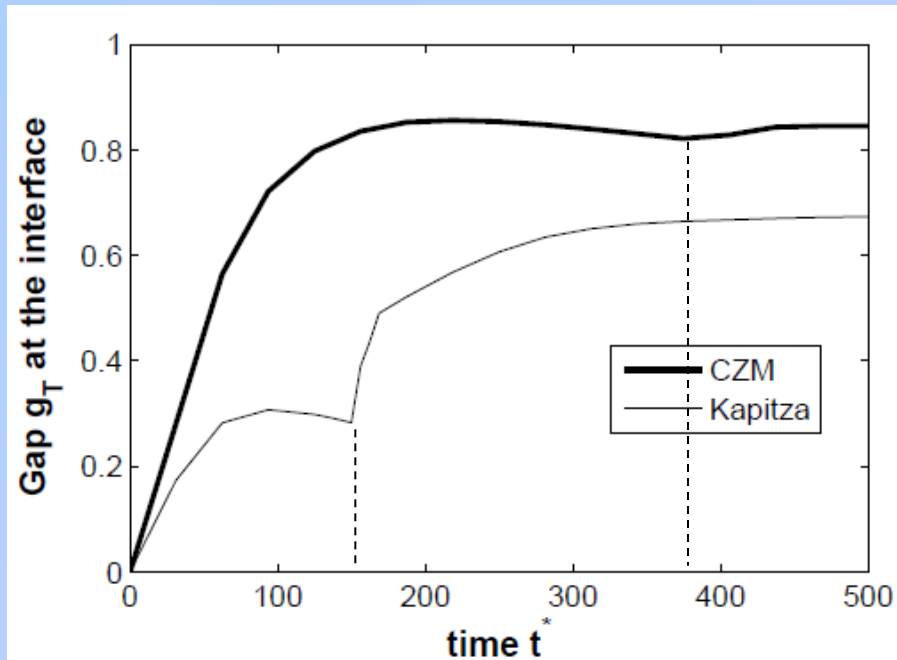


$$\sigma_{max}^* = 0.032, \quad g_{nc}^* = 0.05$$

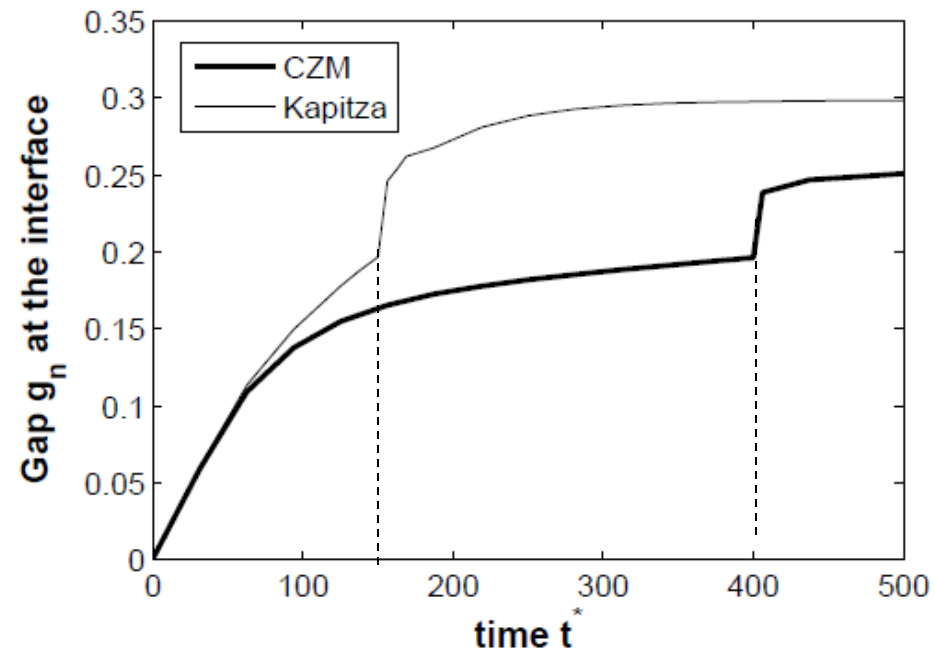
Results 3

Let us compare the CZM results with $k_{int}=1/r_{int}$:

TEMPERATURE GAP



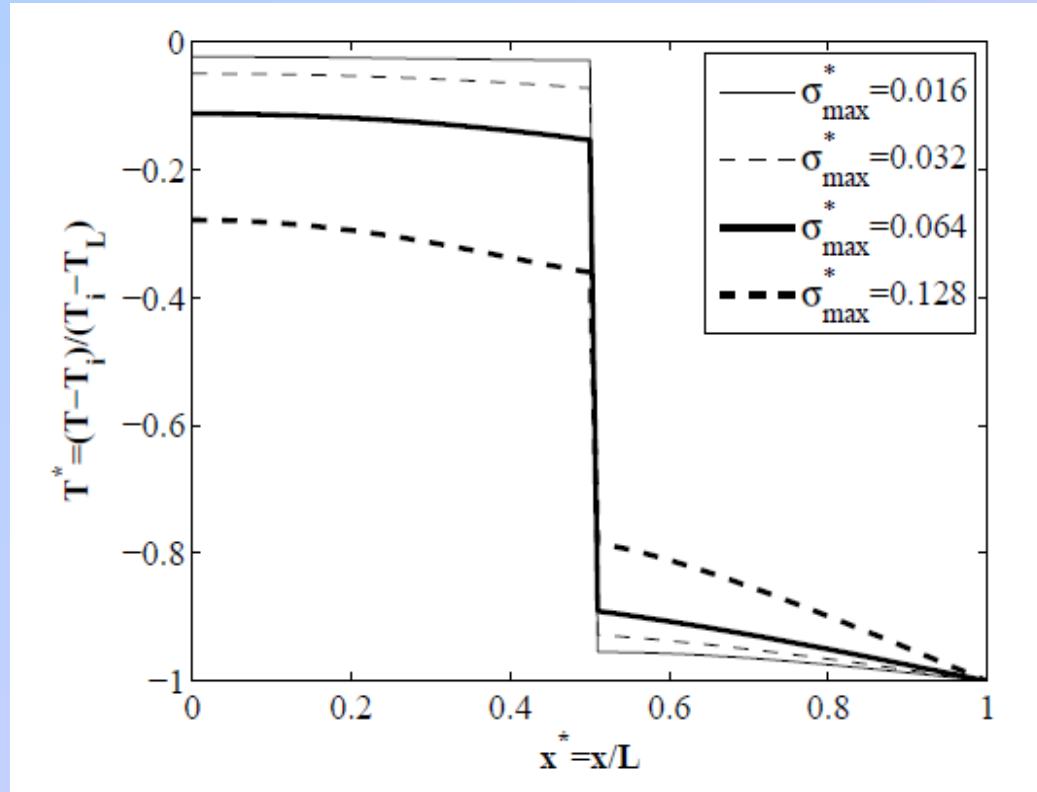
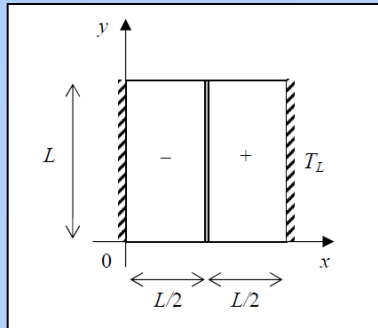
DISPLACEMENT GAP



Neglecting thermoelastic coupling leads to different thermal and elastic behaviors..

Results 4

Temperature field as σ_{max}^* varies ($t^*=200$)



An analogous behavior is observed by modifying g_{nc}^* (σ_{max}^* *fixed*)



Conclusions



A thermo-mechanical CZM inspired by contact mechanics between rough surfaces has been put forward: the interface conductivity results to be a function of cohesive stresses

Thermo-elastic effects related to the transient regime are investigated, with particular attention to:

- i) the time evolution of the temperature and displacement
- ii) the influence of the cohesive parameters on fracture initiation

Future perspectives:

- i) numerical solution of 2D problems in the presence of multiple micro-cracks
- ii) coupling between the electric and the thermal fields



Acknowledgements



FIRB Future in Research

**Structural Mechanics Models
for Renewable Energy Applications, RBFR107AKG**

**Thanks
for your attention**